



Laboratory for Underwater Systems and Technologies (LABUST)

LABUST, University of Zagreb, Faculty of Electrical Engineering and Computing prof. dr. sc. Nikola Mišković



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Int'l 17

23 national



















Active projects 4 EUROPEAN PROJECTS

- INTERREG InnovaMARE
- HE MONUSEN
- HE UWIN-LABUST
- INTERREG MARBLE

4 NATIONAL PROJECTS

- ZCI DATACROSS
- Multipurpose Unmanned Ship
- Multifunctional Smart Buoys
- HEKTOR

1 ONR PROJECT

ROADMAP

1 Schmidt Ocean Institute PROJECT

• SOUND

- Finished projects
- H2020 PROJECTS
 - H2020-Twinn EXCELLABUST
 - H2020 Fire+ PLADYFLEET
 - H2020-Teaming ACROSS
 - H2020 FET Launchpad APAD
 - H2020 CROBOHUB
 - H2020-INFRA EUMarineRobots
 - H2020 ROBOCOMM++
 - H2020-FET SUBCULTRON

• FP7 PROJECTS

- FP7-INFRA EUROFLEETS2
- FP7-ICT CADDY
- FP7-SME CART
- FP7-REGPOT CURE

• OTHER EU PROJECTS

- INTERREG BLUEMED
- INTERREG SIOI
- DG-ECHO E-URready4OS
- DG-ECHO URready40S

- Finished projects
- OTHER INT'L
 - ADRIATIC
- NATIONAL
 - H2020-Twinn EXCELLABUST
 - HRZZ CroMarX
 - bilateral China
 - ESF INFRA-LAPOST





EXCELLABUST

Excelling LABUST in marine robotics

Funding scheme: H2020 – TWINNING Total budget: 1.014.551,00 EUR Start date: 01/01/2016; Duration: 36 months **Coordinator: UNIZG-FER**



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 691980.







Nazionale

Ricerche

delle



of

LIMERICK

OLLSCOIL LUIMNIGH

Iniversitat de Girona istitut de Recerca en Visió



| Proposal Evaluation Form | | | | | |
|---|---|---|--|--|--|
| European Conversione | EUROPEAN COMMISSION Horizon 2020 - Research and Innovation Framework Programme | Evaluation Summary Report - Coordination and support actions | | | |
| Call: Funding scheme: Proposal number: Proposal acronym: Duration (months): Proposal title: Activity: | H2020-TWINN-2015 Coordination & support action 691980 EXCELLABUST 36 Excelling LABUST in marine robotics H2020-TWINN-2015-1 | | | | |
| Evaluation Result | | | | | |

Total score: 15.00 (Threshold: 10)

Form information

SCORING

Scores must be in the range 0-5.

Interpretation of the score:

- 0- The proposal fails to address the criterion or cannot be assessed due to missing or incomplete information.
- 1- Poor. The criterion is inadequately addressed, or there are serious inherent weaknesses.
- 2- Fair. The proposal broadly addresses the criterion, but there are significant weaknesses.
- 3- Good. The proposal addresses the criterion well, but a number of shortcomings are present.
- 4- Very good. The proposal addresses the criterion very well, but a small number of shortcomings are present.
- 5- Excellent. The proposal successfully addresses all relevant aspects of the criterion. Any shortcomings are minor.



Budget

| N. | Proposer name | Country | Total Cost | % | Grant Requested | % |
|----|--|---------|------------|--------|--------------------|--------|
| 1 | SVEUCILISTE U ZAGREBU FAKULTET ELEKTROTEHNIKE I RACUNARSTVA | HR | 381,225 | 37.58% | 381,225 | 37.58% |
| 2 | CONSIGLIO NAZIONALE DELLE RICERCHE | IT | 201,056 | 19.82% | 201,056 | 19.82% |
| 3 | UNIVERSITAT DE GIRONA | ES | 203,927 | 20.10% | 203,927 | 20.10% |
| 4 | UNIVERSITY OF LIMERICK | IE | 228,342 | 22.51% | 228,342 | 22.51% |
| | Total: | | 1,014,550 | | 1,014,550 | |



Project goals and objectives

- The main goal of EXCELLABUST project
 - address networking gaps and deficiencies between UNIZG-FER and internationally leading counterparts at EU level, by significantly strengthening marine robotics research within LABUST
- Aligned with Robotics 2020 Multi- Annual Roadmap (MAR)

| SRD 1. Perception and m | apping SRD 2. Ac guidance | vanced navigation, and control (NGC) | SRD 3. Autonomy and cogniti | | |
|--|---|---|-----------------------------|---|--|
| 1.1. Underwater multi-sensory ma 1.2. Underwater 3D sensing 1.3. Map-based localization (+ SLA | 2.1. Fault-tolera pping 2.2. Robust NGC 2.3. Advanced h M) 2.4. Cooperative marine vehi | 2.1. Fault-tolerant control 2.2. Robust NGC in real marine environments 2.3. Advanced human-machine interfaces 2.4. Cooperative control of heterogeneous marine vehicles | | mission planning tive path planning with i essing and interpretation | |
| Technology | Research staff | Infrastruc | ture | Field trials | |







IMPACT

KEY IMPACT INDICATORS

KII 1. PUBLICATIONS



9 journal publications with IF (15 in total)



14 conference publications (51 in total)

99970% increase in citations





proposals (36 international and 7 national)



KII 3. INNOVATION AND CONNECTION WITH INDUSTRY

2 startup company

7 collaboration agreements with businesses 2 innovative products

KII 4. EXTENT

OF SYNERGY

7 joint events organized

46% joint publications

5 collaboration agreements with research institutions





This project has received funding from the European Union's Horizon 2020 research





UNIVERSITY OF LIMERICK



Universitat de Girona Institut de Recerca en Visió per Computador i Robòtica







INFRA LAPOST

Istraživačka infrastruktura Laboratorija za podvodne sustave i tehnologije (INFRA-LAPOST)

Naziv korisnika sredstava: Fakultet elektrotehnike i računarstva, Sveučilište u Zagrebu Lokacija sjedišta korisnika: Grad Zagreb Prioritetna os: Jačanje gospodarstva primjenom istraživanja i inovacija Vrsta natječajnog postupka: Ograničeni (privremeni) Fond: Europski fond za regionalni razvoj (ERDF) Operativni program: Operativni program Konkuretnost i kohezija Razdoblje provedbe projekta: 01. listopada 2018. – 30. rujna 2020. godine Ukupna vrijednost projekta (HRK): 1.500.000,00 kn Ukupni iznos EU sufinanciranja (HRK): 1.500.000,00 kn











UWIN~LABUST



UWIN-LABUST

ERA Chair in Internet of Underwater Things at LABUST

Funding scheme: HE – ERA Chair Total budget: 2,5 mil EUR

Start date: 01/01/2023; Duration: 60 months





- 1. The ERA Chair holder will be Prof. Roee Diamant, an outstanding researcher and innovator in the Internet of Underwater Things research area, currently employed with the University of Haifa (Israel).
- 2. The ERA Chair team includes
 - a research team consisting of a Group Leader, 2 postdocs and 2 PhD students with the objective to work towards achieving excellence in the Internet of Underwater Things research area, and one
 Technology Transfer Officer whose main objective is to ensure sustainability.



Right-to-react-pilot cover letter

| | 1. EXCELLENCE | 2. IMPACT | 3. IMPLEMENTATION | |
|-----------|----------------------------|--------------------------------|----------------------------|---------------------------|
| Expert 1: | 7 + | 5 + | 6+ | 18 + (62%) |
| | 4 – | 3 – | 4 - | 11 - |
| Expert 2: | 13 + | 14 + | 12 + | 39 + (81,25%) |
| | 4 – (2 minor shortcomings, | 4 - (3 minor shortcomings, 1) | 1 – (minor shortcoming) | 9 - (6 minor, 3) |
| | 2 shortcomings) | shortcoming) | | short) |
| Expert 3: | 7 + | 7 + | 12 + | 26 + (81,25%) |
| | 2 – (2 shortcoming) | 2 – (2 shortcomings) | 2 - (1 minor shortcoming) | 6 – (1 minor, 4 short) |
| | 27 + (73%) | 26 + (74,3) | 30 + (81%) | |
| | 10 – (2 minor, 4 short) | 9 - (3 minor, 3 short) | 7 – (2 minor) | |



Associated with document Ref. Ares(2022)5097438 - 13/07/2022.

| Proposal Evaluation Form | | | | | | | | |
|---|---|------------------------|------------|---|--------------------|---|--|--|
| $\langle \rangle$ | EUROPEAN COMMISSION Horizon Europe Framework Programme (HORIZON) | | | Evaluation Summary Report - Coordination and support actions | | | | |
| Call: Type of action: Proposal number: Proposal acronym: Duration (months): Proposal title: Activity: | HORIZON-WIDERA-2022-TALENT HORIZON-CSA 101086340 UWIN-LABUST 60 ERA Chair in Internet of Underwater ENV + MED + ENG + MAT/SOC | S-01 Things at LABU | ST | | | | | |
| N. | Proposer name | Country | Total Cost | % | Grant Requested | % | | |
| CVEUCILICTE 1 | | | | | | | | |

| Ν. | Proposer name | Country | Total Cost | % | Requested | % |
|----|--|---------|-------------------|--------|-------------------|--------|
| 1 | SVEUCILISTE U ZAGREBU FAKULTET ELEKTROTEHNIKE I RACUNARSTVA | HR | 2,399,225 | 96.00% | 2,399,225 | 96.00% |
| 2 | UNIVERSITY OF HAIFA Total: | IL. | 100,075 2,499,300 | 4.00% | 100,075 2,499,300 | 4.00% |
| | | | | | | |

Abstract:

UWIN-LABUST project aims to create conditions and opportunities at the University of Zagreb Faculty of Electrical and Engineering and Computing (UNIZG-FER) in Croatia for high quality researchers and research managers to move and engage to achieve excellence in a sustainable manner within the area of Internet of Underwater Things (IoUT), at the Laboratory for Underwater Systems and Technologies (LABUST).

The objectives of the UWIN-LABUST project are: 1) to recruit Prof. Roee Diamant from University of Haifa as ERA Chair holder who will establish his own team consisting of 3 post-docs, a technology transfer officer, and a group leader; 2) to achieve excellence in the research area of IoUT (a network of smart interconnected underwater objects) with particular focus on 3 strategic research domains: a) underwater sensor communications. b) underwater acoustic signal processing, and c) underwater collaborative autonomy; 3) to ensure sustainability of the achieved excellence; and 4) to increase UWIN-LABUST group scientific involvement and visibility.

These objectives will be reached through a set of strategic measures: expert visits and outgoing study visits for providing knowledge transfer; research & innovation management trainings and establishment of Technology Transfer Office for transferring results from academia to industry; new MSc and PhD courses to ensure knowledge transfer to new generations; organization of workshops, summer schools and conferences for strengthening links to industry, end-users, and the scientific community.

Ministry of Science and Education of Croatia has provided a letter of commitment guaranteeing additional financial support for equipment and infrastructure to UWIN-LABUST project from European Structural and Investment Funds. Dean of UNIZG-FER also committed to ensuring additional financial research support.

Evaluation Summary Report

Evaluation Result

Total score: 12.50 (Threshold: 10)





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